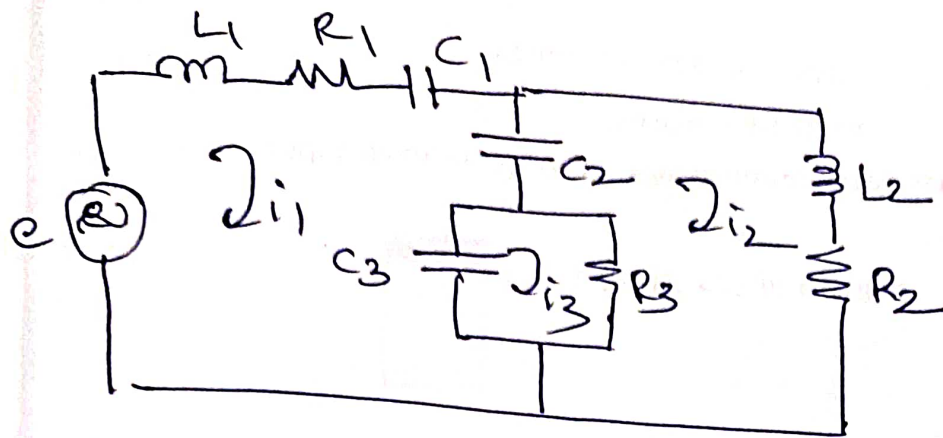


The force voltage analogy of a mechanical translational system is given obtain analogous mechanical system



Applying KVL to the loop i_1, i_2 & i_3

$$e = L_1 \frac{di_1}{dt} + R_1 i_1 + \frac{1}{C_1} \int i_1 dt + \frac{1}{C_2} \int (i_1 - i_2) dt + \frac{1}{C_3} \int (i_1 - i_3) dt$$

in terms of q

$$e = L_1 \frac{d^2 q_1}{dt^2} + R_1 \frac{dq_1}{dt} + \frac{1}{C_1} q_1 + \frac{1}{C_2} (q_1 - q_2) + \frac{1}{C_3} (q_1 - q_3)$$

| | |
|---|--|
| $F \rightarrow V$ | |
| $v \rightarrow \dot{q}$ | |
| $x \rightarrow q$ | |
| $\frac{dx}{dt} \rightarrow \frac{dq}{dt}$ | |
| $\frac{dx}{dt^2} \rightarrow \ddot{q}$ | |
| $x \rightarrow \int \dot{q} dt$ | |
| $M \rightarrow L$ | |
| $B \rightarrow R$ | |
| $k \rightarrow \frac{1}{C}$ | |

Corresponding analogous mechanical sys equation

$$f = M_1 \frac{d^2 x_1}{dt^2} + B_1 \frac{dx_1}{dt} + K_1 x_1 + \frac{K_2}{2} (x_1 - x_2) + \frac{K_3}{2} (x_1 - x_3)$$

loop 2

$$0 = \frac{1}{C_2} \int (i_2 - i_1) dt + L_2 \frac{di_2}{dt} + R_2 i_2 + R_3 (i_2 - i_3)$$

$$= \frac{1}{C_2} \left(\frac{dq_2}{dt} - \frac{dq_1}{dt} \right)$$

①

①

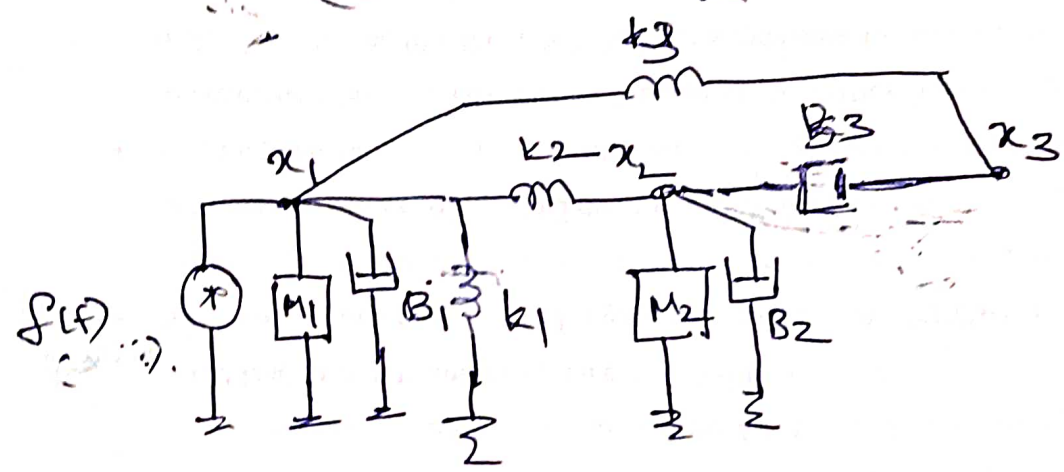
Corresponding mechanical eqs differential equation

$$0 = \frac{k_2}{s^2} (x_2 - x_1) + M_2 \frac{d^2 x_2}{dt^2} + B_2 \frac{dx_2}{dt} + B_3 \frac{d}{dt} (x_2 - x_3)$$

Loop 3

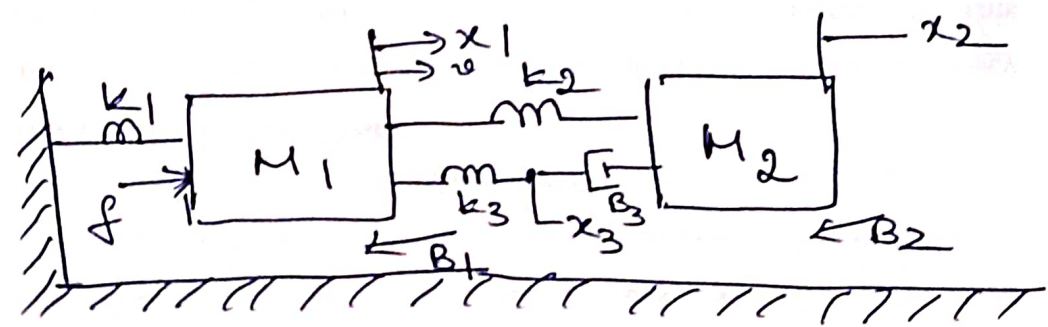
$$\frac{1}{C_3} \int (i_3 - i_1) dt + R_3 (i_3 - i_2) = 0$$

$$0 = \frac{k_3}{s^2} (x_3 - x_1) + B_3 \frac{d}{dt} (x_3 - x_2)$$

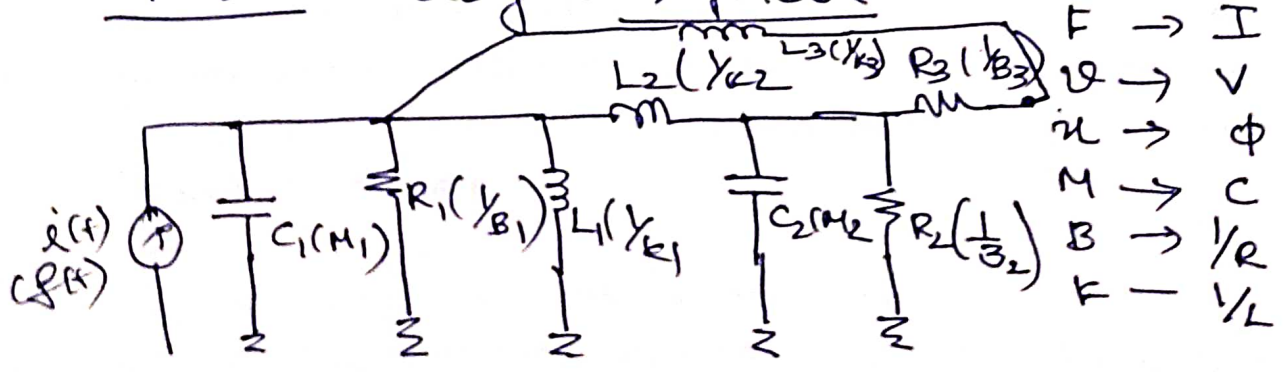


Mechanical n/w

Mechanical system

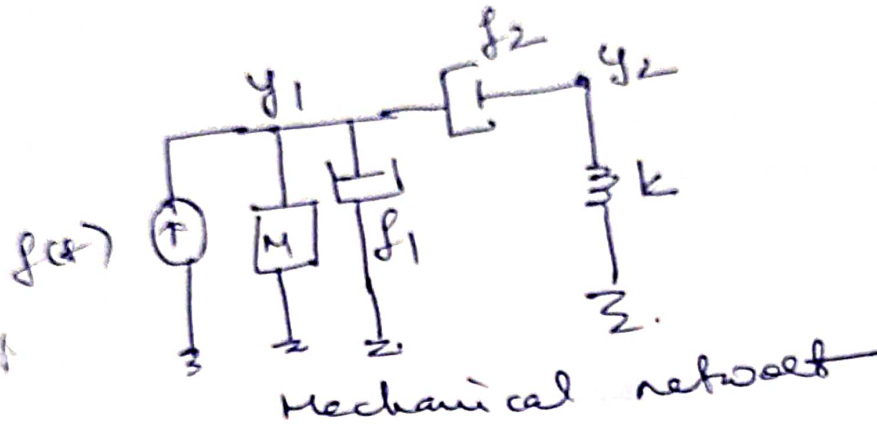
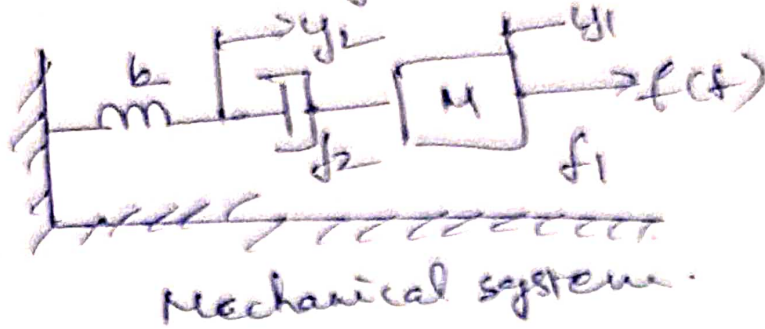


F-I analogous system

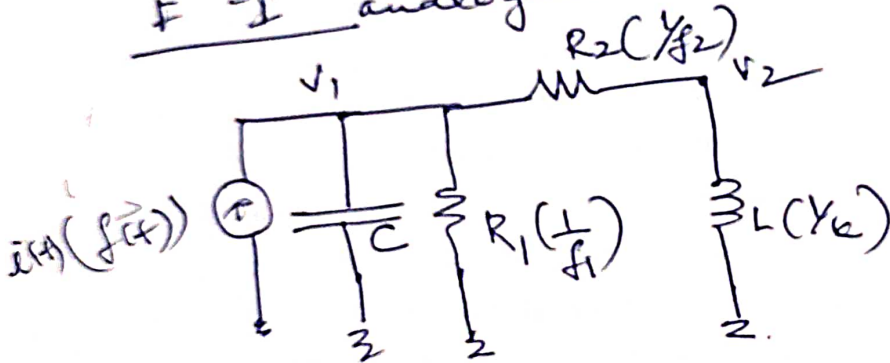


- F → I
- u → V
- x → φ
- M → C
- B → 1/R
- k → 1/L

Consider mechanical system
 Draw Mechanical network
 F-I analogue network
 P-V analogue network.

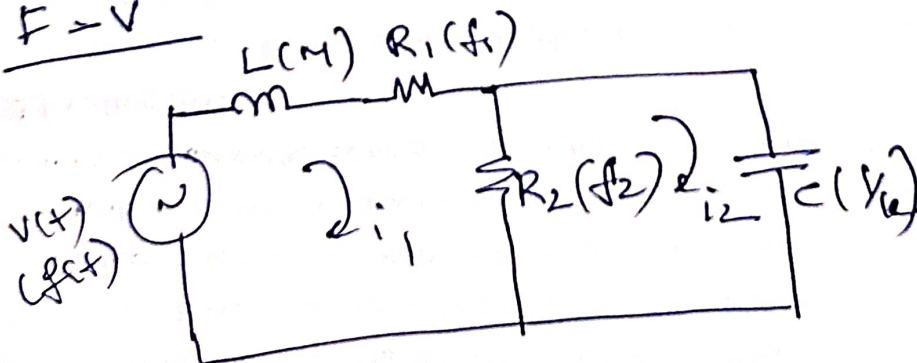


F-I analogue network



$F \rightarrow I$
 $x \rightarrow v$
 $x \rightarrow \phi$
 $M \rightarrow L$
 $B \rightarrow R$
 $k \rightarrow 1/L$

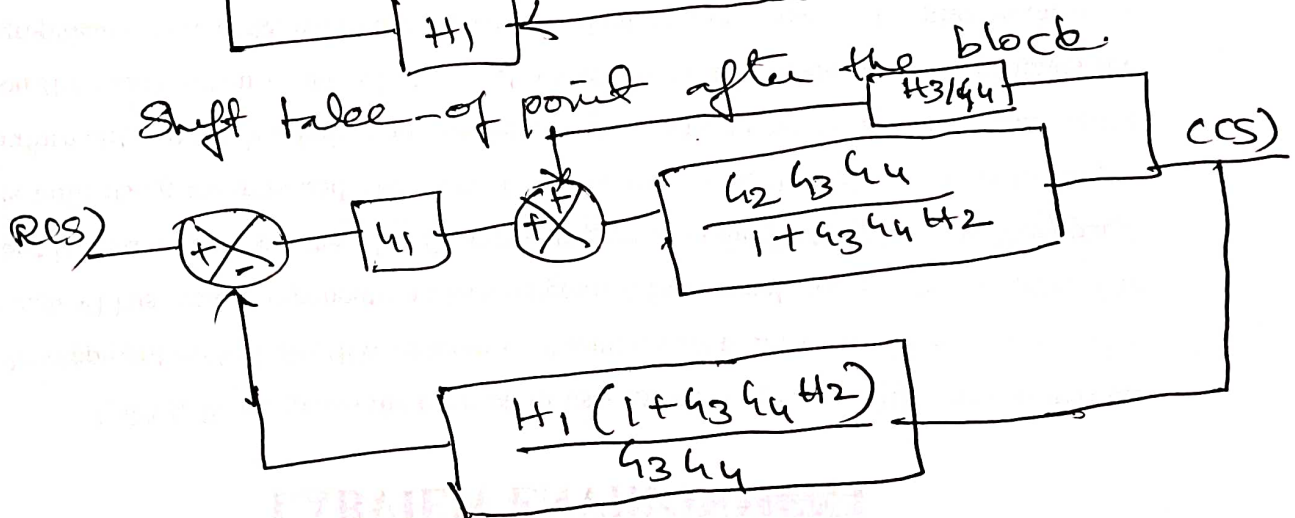
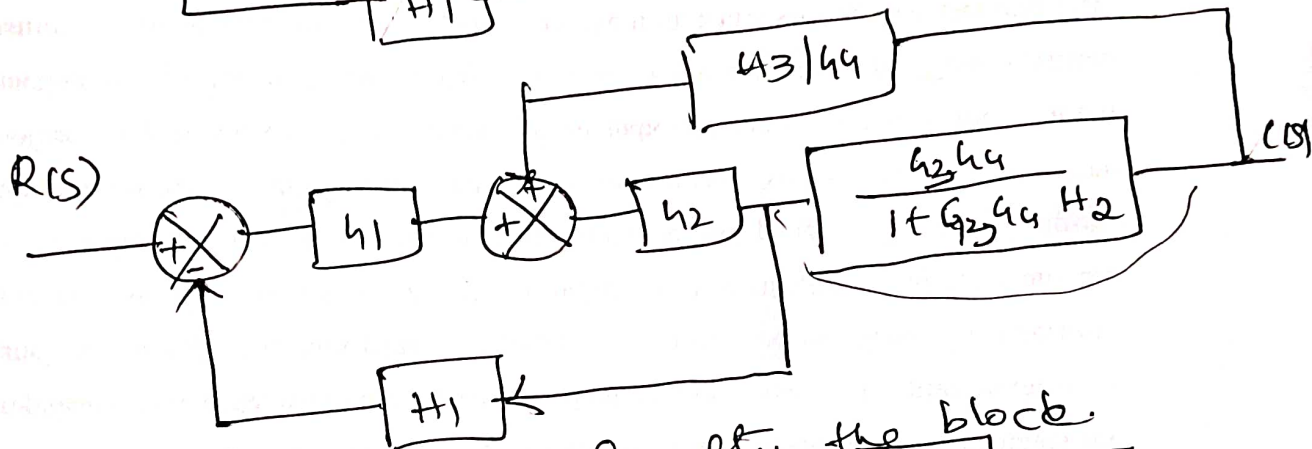
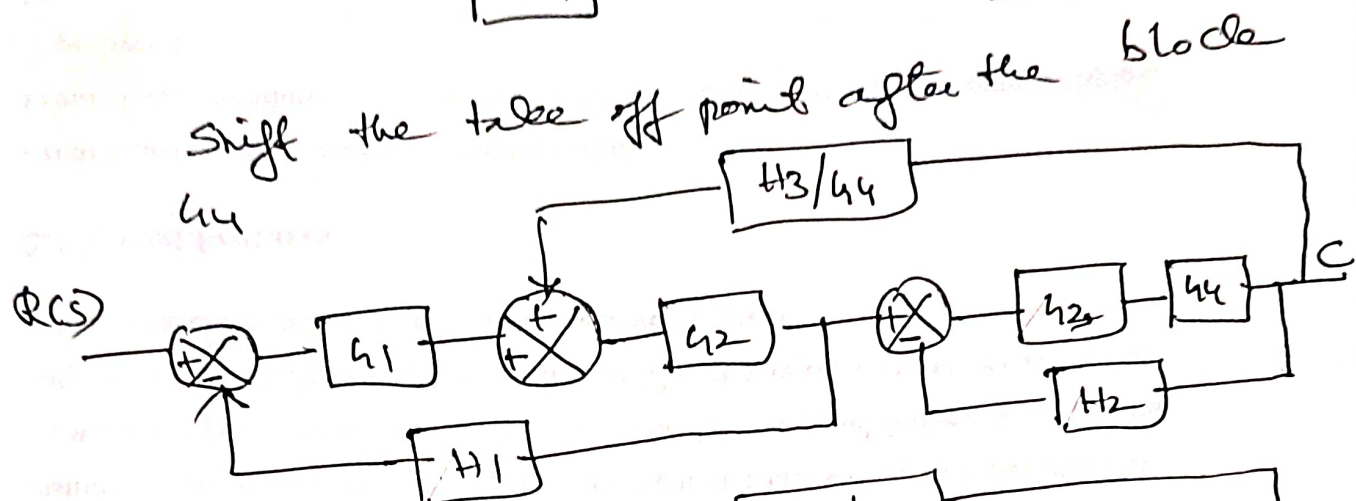
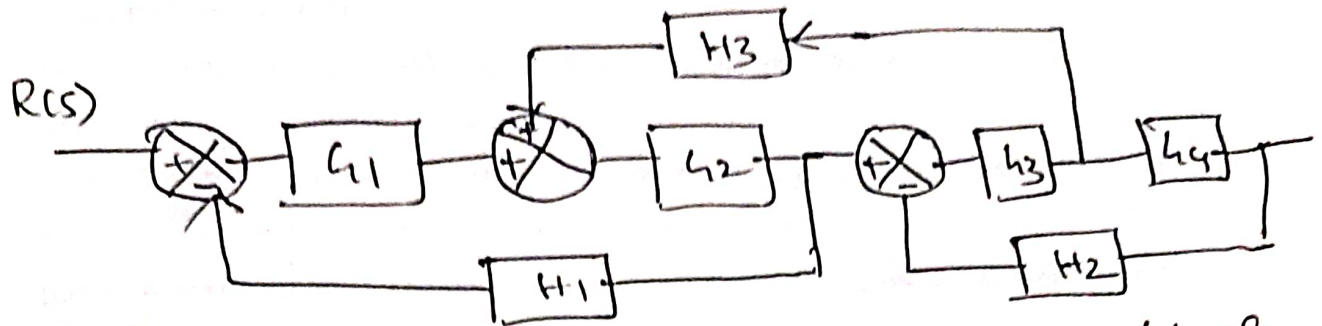
F-V



$F \rightarrow V$
 $x \rightarrow i$
 $x \rightarrow q$
 $x \rightarrow \int i dt$
 $M \rightarrow L$
 $B \rightarrow R$
 $k \rightarrow 1/C$

(1)

1) Determine transfer function by reducing the block diagram shown in fig



Eliminating feedback loop (+ve)

(2)

$$TF = \frac{G}{1 - GH}$$

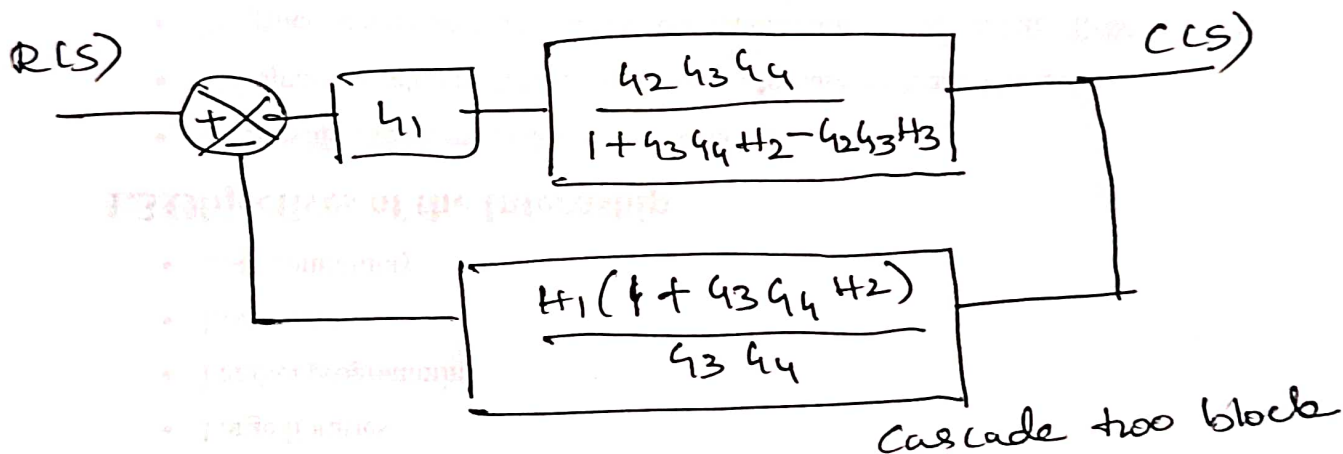
$$= \frac{G_2 G_3 G_4}{1 + G_3 G_4 H_2}$$

$$1 - \frac{G_2 G_3 G_4}{1 + G_3 G_4 H_2} \times \frac{H_3}{G_4}$$

$$= \frac{G_2 G_3 G_4}{1 + G_3 G_4 H_2}$$

$$\frac{1 + G_3 G_4 H_2 - G_2 G_3 H_3}{1 + G_3 G_4 H_2}$$

$$= \frac{G_2 G_3 G_4}{1 + G_3 G_4 H_2 - G_2 G_3 H_3}$$



$$TF = \frac{G}{1 + GH}$$

(3)

$$TF = \frac{G_1 G_2 G_3 G_4}{1 + G_3 G_4 H_2 - G_2 G_3 H_3}$$

$$1 + \frac{G_1 G_2 G_3 G_4}{1 + G_3 G_4 H_2 - G_2 G_3 H_3} \times \frac{H_1 (1 + G_3 G_4 H_2)}{G_3 G_4}$$

$$= \frac{G_1 G_2 G_3 G_4}{1 + G_3 G_4 H_2 - G_2 G_3 H_3} \times \frac{H_1 (1 + G_3 G_4 H_2)}{G_3 G_4}$$

$$= \frac{G_1 G_2 G_3 G_4 H_1 (1 + G_3 G_4 H_2)}{1 + G_3 G_4 H_2 - G_2 G_3 H_3 + G_1 G_2 H_1 (1 + G_3 G_4 H_2)}$$

$$= \frac{G_1 G_2 G_3 G_4 H_1 (1 + G_3 G_4 H_2)}{1 + G_3 G_4 H_2 - G_2 G_3 H_3 + G_1 G_2 H_1 + G_1 G_2 H_1 H_2 G_3 G_4}$$

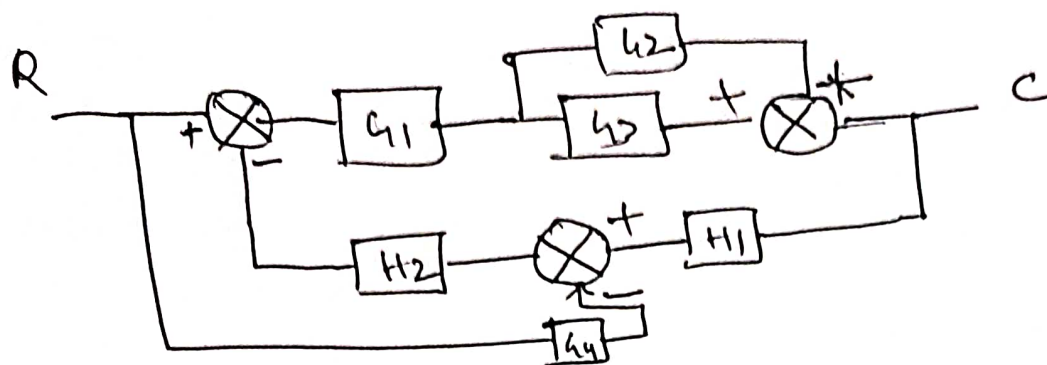
$$\frac{C(s)}{R(s)} TF = \frac{G_1 G_2 G_3 G_4 H_1 (1 + G_3 G_4 H_2)}{1 + G_3 G_4 H_2 - G_2 G_3 H_3 + G_1 G_2 H_1 + G_1 G_2 H_1 H_2 G_3 G_4}$$

$$R(s) \rightarrow \boxed{\frac{G_1 G_2 G_3 G_4 H_1 (1 + G_3 G_4 H_2)}{1 + G_3 G_4 H_2 - G_2 G_3 H_3 + G_1 G_2 H_1 + G_1 G_2 H_1 H_2 G_3 G_4}}$$

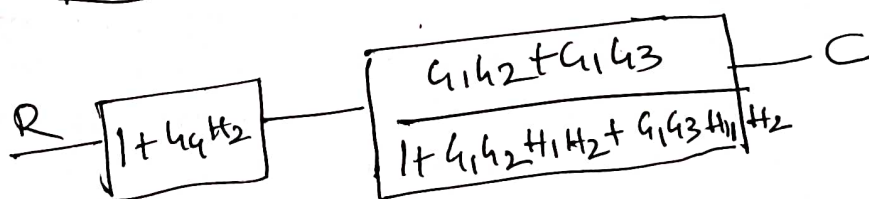
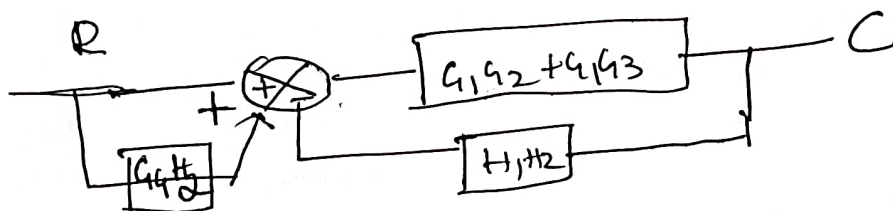
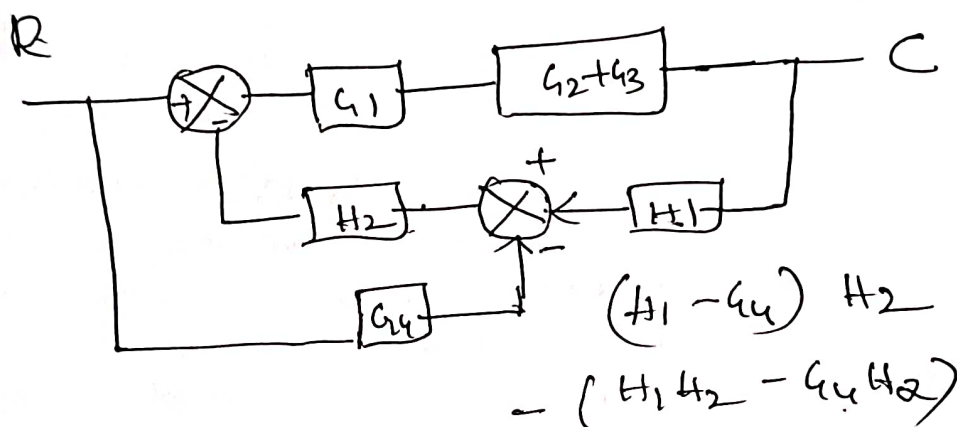
MINDO CLOUD

Determine transfer function

(39)



G_2 & G_3 are in parallel



$$TF = \frac{G_1 H_2 + G_1 H_3}{1 + (G_1 H_2 + G_1 H_3) H_1 H_2}$$

